

IEEE Ro-MAN 2019 Program Schedule										
<b>October 14, 2019 (Monday)</b>										
Time	R1	R2	R3	R4	R5	No. of Papers	Room Code	Room Name	Capacity	
07:00-10:00	Registration									
8:30-10:30	WS5	WS10	WS13	WS2	WS1	NA	R1	Sovereign 1	100	
10:30-11:00	Coffee Break						R2	Sovereign 2	100	
11:00-13:00	WS5	WS10	WS13	WS2	WS1	NA	R3	Inspire	60	
13:00-14:00	Lunch						R4	Desire	60	
14:00-17:00	WS5	WS8	WS11	WS6	WS1	NA	R5	Azure	60	
17:00-19:00	Welcome Reception									
<b>October 15, 2019 (Tuesday)</b>										
Time	Track 1	Track 2	Track 3	Track 4	Track 5	No. of Papers	Paper category	Count		
08:30-09:00	Inauguration / Opening Ceremony						Posters	55		
09:00-10:00	Plenary Talk 1						Oral	150		
10:00-10:30	Coffee Break						Total	<b>205</b>		
10:30-12:00	RS1	RS2	RS3	RS4	SS1	30				
12:00-13:00	Lunch									
13:00-14:30	RS5	RS6	RS7	RS8	SS2	30				
14:30-15:00	Coffee Break									
15:00-16:30	RS9	RS10	RS11	RS12	SS3	30				
16:30-17:30	Plenary Talk 2					90				
<b>October 16, 2019 (Wednesday)</b>										
Time	Track 1	Track 2	Track 3	Track 4	Track 5	Number of Papers				
09:00-10:00	Plenary Talk 3									
10:00-10:30	Coffee Break									
10:30-12:00	RS13	RS14	RS15	RS16	SS4	30				
12:00-13:00	Lunch									
13:00-15:00	Poster Session					55				
15:00-15:30	Coffee Break									
15:30-17:00	RS17	RS18	RS19	RS20	SS5	30				
17:00-18:00	Panel Discussion									
18:00-19:00										
19:00-21:30	Banquet / Award Ceremony					<b>115</b>				
<b>October 17, 2019 (Thursday)</b>										
Time	R1	R2	R3	R4	R5	Number of Papers				
08:30-10:30	WS12	WS9	WS7	WS3						
10:30-11:00	Coffee Break									
11:00-13:00	WS12	WS9	WS7	WS3						
13:00-14:00	High Tea & Closing Ceremony									
14:00-18:00	CITY TOUR									

**Paper Distribution Across Sessions**

<b>Tracks</b>	<b>RS1</b>	<b>RS2</b>	<b>RS3</b>	<b>RS4</b>	<b>SS1</b>		<b>RS13</b>	<b>RS14</b>	<b>RS15</b>	<b>RS16</b>	<b>SS4</b>
Paper ID	64	26	36	31	23		155	152	264	30	80
	91	35	41	60	161		176	243	288	58	116
	172	45	44	78	206		190	245	148	123	205
	18	95	62	94	71		260	252	219	267	166
	239	180	73	212	75		209	266	171	179	88
	10	104	77	55	99		215	300	217	102	112
<b>Tracks</b>	<b>RS5</b>	<b>RS6</b>	<b>RS7</b>	<b>RS8</b>	<b>SS2</b>		<b>RS17</b>	<b>RS18</b>	<b>RS19</b>	<b>RS20</b>	<b>SS5</b>
Paper ID	79	24	87	223	183		138	16	115	246	276
	159	68	108	238	210		150	40	231	270	301
	220	175	113	280	298		151	86	240	253	273
	257	178	128	299	162		170	97	17	67	295
	290	218	134	157	193		207	186	194	153	227
	297	265	135	213	271		211	25	27	293	235
<b>Tracks</b>	<b>RS9</b>	<b>RS10</b>	<b>RS11</b>	<b>RS12</b>	<b>SS3</b>		<b>Poster Session Papers</b>				
Paper ID	165	144	139	65	89		81	82	1	309	15
	181	258	146	96	269		29	37	42	43	59
	202	145	158	121	278		98	76	83	103	105
	189	131	187	140	303		110	117	118	119	124
	296	256	191	160	38		136	142	147	154	174
	21	168	259	173	182		177	185	197	199	201
	<b>Key</b>	<b>Regular Session Tracks</b>					208	216	225	230	232
	RS1	Cognitive Interaction Design					234	236	241	247	282
	RS2	Human Robot Interaction					289	305	306	307	308
	RS3	Social Robots - I					310	312	313	314	315
	RS4	Tele-operation and Autonomous Robots					316	317	318	319	320
	RS5	Robots in Education					<b>Key</b>	<b>Regular Session Tracks</b>			
	RS6	Human Centred Robot Design					RS17	Human Robot Collaboration and Cooperation			
	RS7	Social Robots - II					RS18	Linguistic Communication & Dialogue			
	RS8	Situation Awareness and Spatial Cognition					RS19	Robot Companions			

RS9	Cognitive Skills and Meta Models		RS20	Therapy and Rehabilitation		
RS10	HRI and Collaboration in Manufacturing Environment		<b>Key</b>	<b>Special Session Tracks</b>		
RS11	Social Robots - III		SS1	Transparency and Trust in Human Robot Interaction		
RS12	Visual Perception & Autonomous Robots - I		SS2	Social and Affective Robots		
RS13	Machine Learning and Adaptation		SS3	Social Human Robot Interaction of Service Robots		
RS14	Imitation Learning		SS4	Robotics for Rehabilitation		
RS15	Motion Planning, Navigation & Control in Human Centred Environment		SS5	Medical Robotics & Intelligent Control Systems in the Indian Context		
RS16	Visual Perception & Autonomous Robots - II					